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LAMPIRAN

Lampiran 1. Listing program

```
#include "Nex tion.h"

const int analogPin = A1;

const int sensorPin = A0;

const int pinADC = A2;

int sensitivitas = 185; //tegantung sensor arus yang digunakan.
yang ini 5A
int nilaiadc= 00;
int value = 0;
int teganganoffset = -2500; //nilai pembacaan offset saat tidak
ada arus yang lewat
double tegangan = 00;
double nilaiarus = 00;

float sensorValue;
float voltageOut;

float temperatureC;
float temperatureF;
float Vmodul = 0.0;
float hasil = 0.0;
float R1 = 600000.0;
float R2 = 33000.0;

// uncomment if using LM335
//float temperatureK;

// Declare your Nex tion objects - Example (page id = 0.
component id = 1. component name = "b0")
NexText t2 = NexText(0. 9. "t2");
NexText t3 = NexText(0. 10. "t3");
NexText t8 = NexText(0. 15. "t8");
NexText t6 = NexText(0. 13. "t6");
NexText t7 = NexText(0. 14. "t7");

void setup(void) {
    pinMode(sensorPin. INPUT);
    pinMode(analogPin. INPUT);

    pinMode (pinADC. INPUT);

    value = analogRead(analogPin);
    Vmodul = (value * 3.512) / 1023.0;
    hasil = Vmodul / (R2 / (R1 + R2));

    Serial.begin(9600);

    nexInit();
}
```

```

}

void loop(void) {

    value = analogRead(analogPin);
    Vmodul = (value * 3.512) / 1023.0;
    hasil = Vmodul / (R2 / (R1 + R2)); // reads the analog input
from the IR distance sensor

    value_D0 = digitalRead(IN_D0); // reads the digital input from
the IR distance sensor

    sensorValue = analogRead(sensorPin);
    voltageOut = (sensorValue * 5000) / 524;

    // calculate temperature for LM35 (LM35DZ)
    temperatureC = voltageOut / 10;
    temperatureF = (temperatureC * 1.8) + 32;

    nilaiadc = analogRead(pinADC);
    tegangan = (nilaiadc / 2024.0) * 5000;
    nilaiarus = ((tegangan - teganganoffset) / sensitivitas);

    // calculate temperature for LM335
    //temperatureK = voltageOut / 10;
    //temperatureC = temperatureK - 273;
    //temperatureF = (temperatureC * 1.8) + 32;

    //calculate temperature for LM34
    //temperatureF = voltageOut / 10;
    //temperatureC = (temperatureF - 32.0)*(2.0/7.0);

    String command = "t2.txt=\""+String(temperatureC)+"\""; //
mengirim data temperatur ke t0 nextion
    Serial.print(command);
    Serial.write(0xff);
    Serial.write(0xff);
    Serial.write(0xff);

    String command1 = "t3.txt=\""+String(temperatureF)+"\""; //
mengirim data fahrenheit ke t1 nextion
    Serial.print(command1);
    Serial.write(0xff);
    Serial.write(0xff);
    Serial.write(0xff);

    String command2 = "t8.txt=\""+String(hasil)+"\""; // mengirim
data value_A0 ke t6 nextion
}

```

```
Serial.print(command2);
Serial.write(0xff);
Serial.write(0xff);
Serial.write(0xff);

String command3 = "t6.txt=\""+String(tegangan)+"\""; // mengirim data tegangan ke t6 nextion
Serial.print(command3);
Serial.write(0xff);
Serial.write(0xff);
Serial.write(0xff);

String command4 = "t7.txt=\""+String(nilaiarus)+"\""; // mengirim data nilaiarus ke t6 nextion
Serial.print(command4);
Serial.write(0xff);
Serial.write(0xff);
Serial.write(0xff);

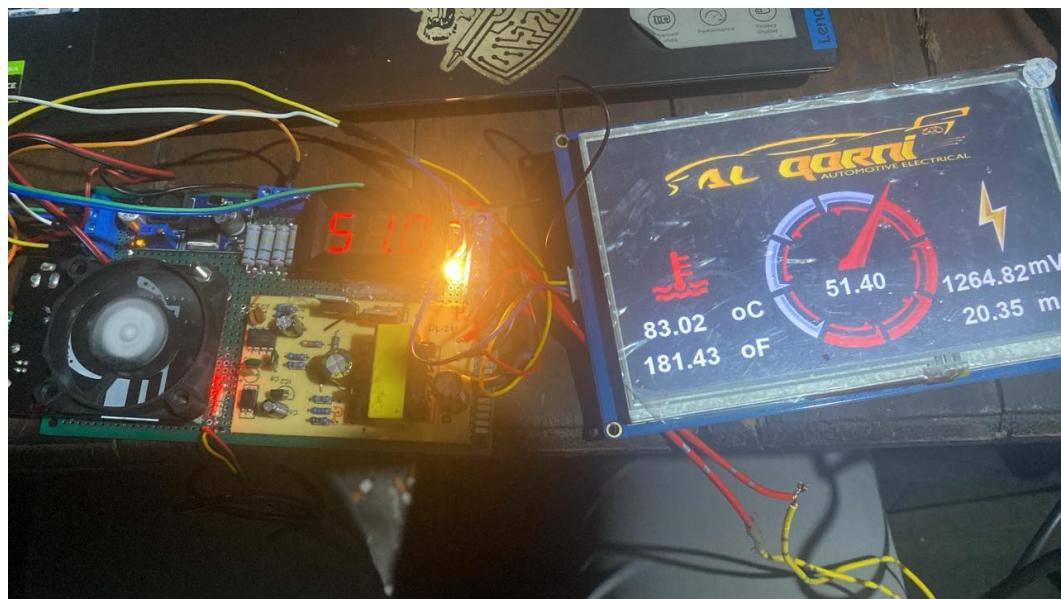
delay(5000);

}
```

Lampiran 2. Perakitan komponen alat penelitian



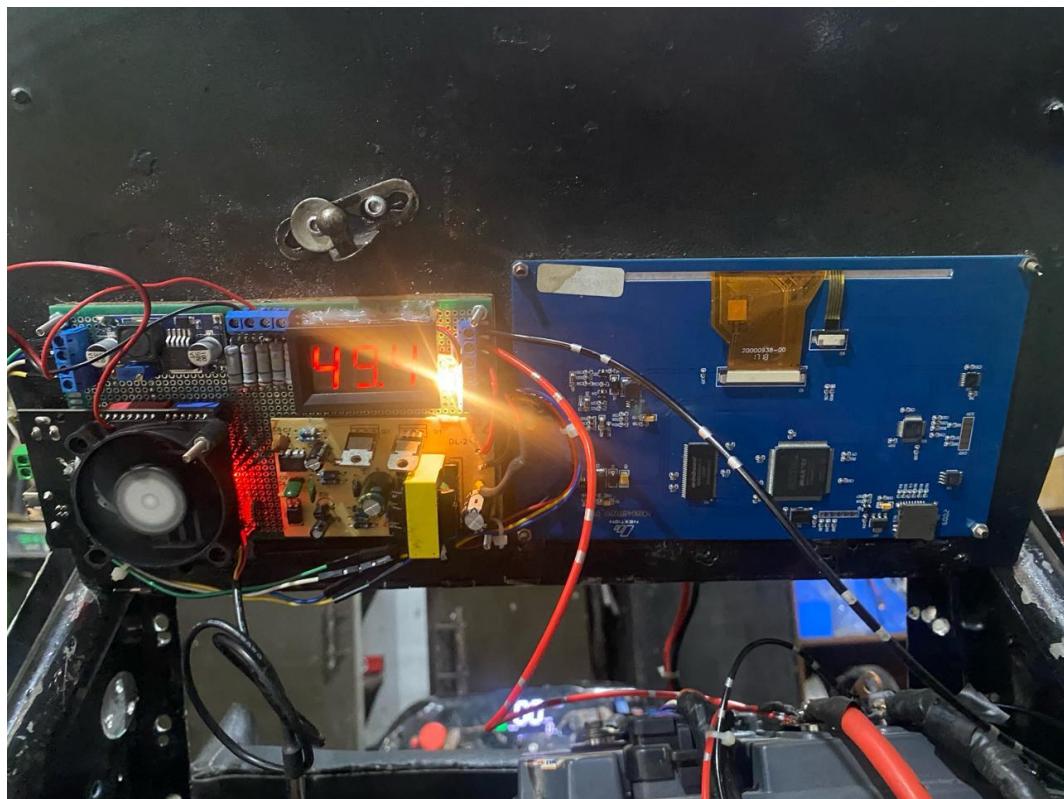
Lampiran 3. Pengetesan alat sebelum diaplikasikan pada mobil



Lampiran 4. Pengecekan tegangan baterai sebagai Ipower supply



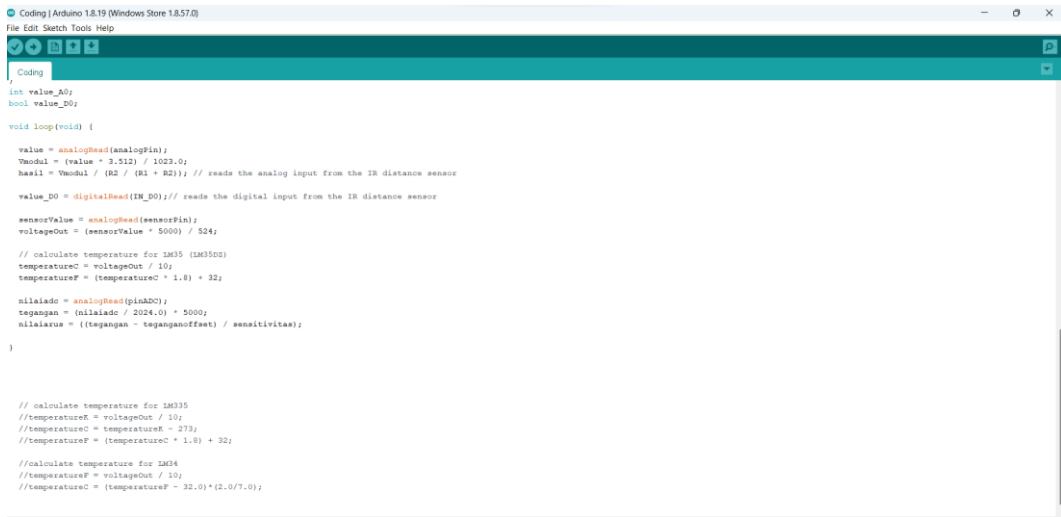
Lampiran 5. Peletakan alat penelitian pada mobil



Lampiran 6. Tampilan instalasi lcd agar mudah dilihat



Lampiran 7. Proses pembuatan program



The screenshot shows the Arduino IDE interface with the following details:

- Title Bar:** Coding | Arduino 1.8.19 (Windows Store 1.8.57.0)
- Menu Bar:** File Edit Sketch Tools Help
- Code Area:** The code is written in C++ for an Arduino sketch. It includes declarations for analog pins A0 and D0, and digital pin IN_D0. The code reads analog values from these pins, performs calculations to convert them into temperature and distance values, and then prints these values to the serial monitor.

```
int value_A0;
bool value_D0;
int value_IN_D0;

void loop(void) {
    value = analogRead(analogPin);
    Vmodul = (value * 3.512) / 1023.0;
    hasil_I = Vmodul / (R2 / (R1 + R2)); // reads the analog input from the IR distance sensor
    value_D0 = digitalRead(IN_D0); // reads the digital input from the IR distance sensor
    sensorValue = analogRead(sensorPin);
    voltageOut = (sensorValue * 5000) / 524;
    // calculate temperature for LM35 (LM3550S)
    temperatureC = voltageOut / 10;
    temperatureF = (temperatureC * 1.8) + 32;
    nilaiadc = analogRead(gilabc);
    tegangan = (nilaiadc / 2048.0) * 5000;
    nilaiarus = ((tegangan - teganganoffset) / sensitivitas);

    // calculate temperature for LM35
    //temperatureK = voltageOut / 10;
    //temperatureC = temperatureK - 273;
    //temperatureF = (temperatureC * 1.8) + 32;

    //calculate temperature for LM34
    //temperatureF = voltageOut / 10;
    //temperatureC = (temperatureF - 32.0)*(2.0/7.0);
}
```

Lampiran 8. Pengambilan data arus

